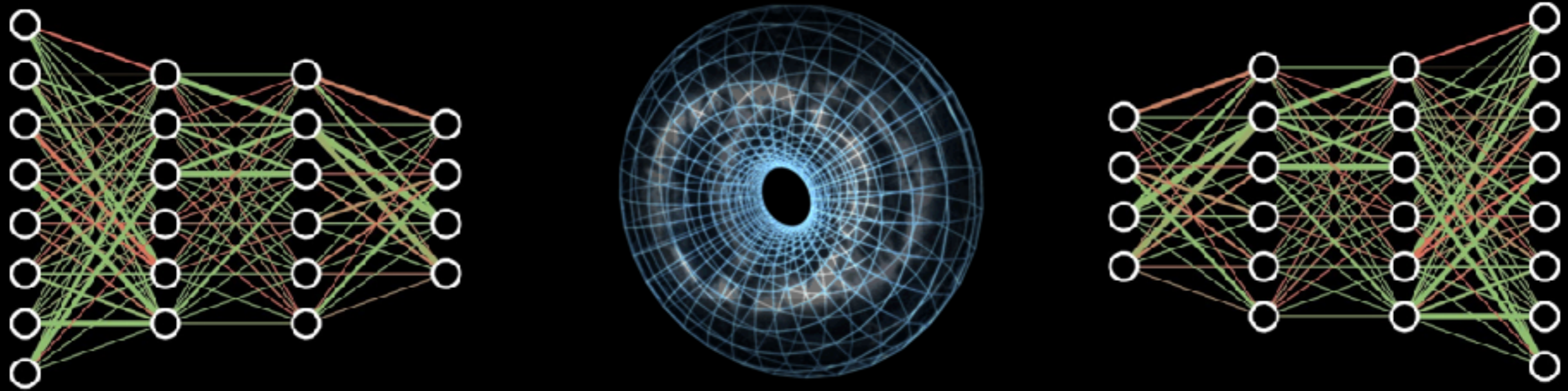


Ubiquitous Machine Learning

deep data representation for next generation applications



SMU O'Donnell Institute Speaker Series, HPC
September 18th, 2024

eric c. larson | eclarson.com
Bobby B. Lyle Endowed Professor in Engineering Innovation
Associate Professor in Computer Science

SMU **Lyle School
of Engineering**



X



Computational Biology & Health Workshop

October 3, 2024. 9:00 AM - 1:00 PM.

(3000 Pegasus Park Drive, Dallas, TX 75247)

Light breakfast and lunch will be served.

[REGISTER HERE](#)



Questions? Contact
Mary.Moua@smu.edu.





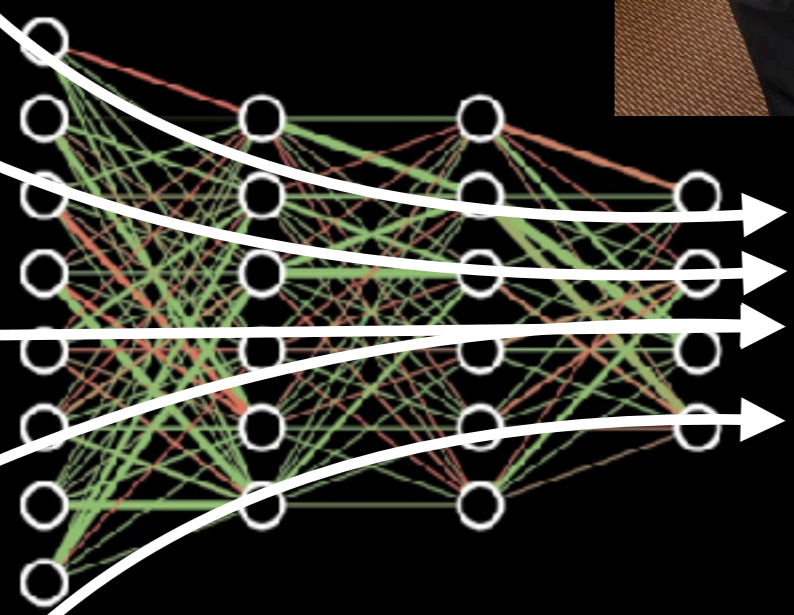
**Matrix
Factorization**


**Sequential
Processing**

**Generative
Networks**

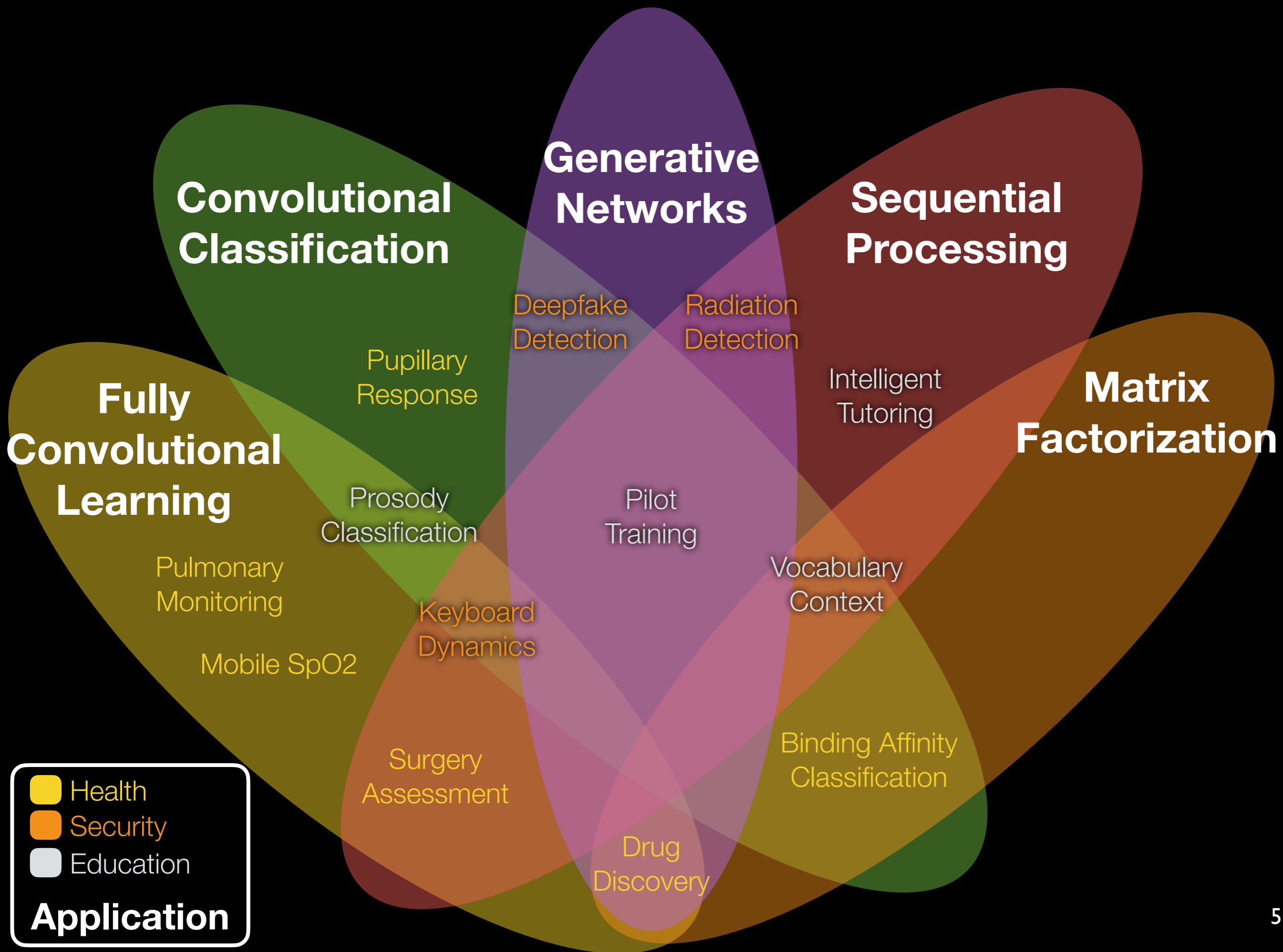
**Convolutional
Classification**

**Fully
Convolutional
Learning**

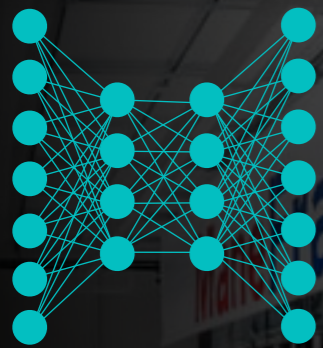


$p(s | k)$ 

$$\arg \max_k \mathbf{E}_{k \in \mathcal{K}} [p(s | k)]$$



Fully Convolutional Learning



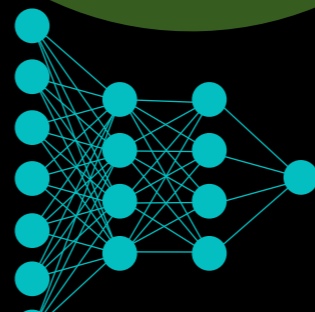
Generative Networks



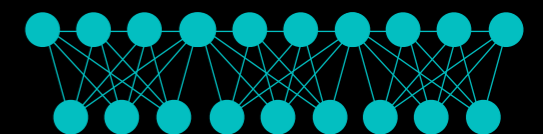
Matrix Factorization



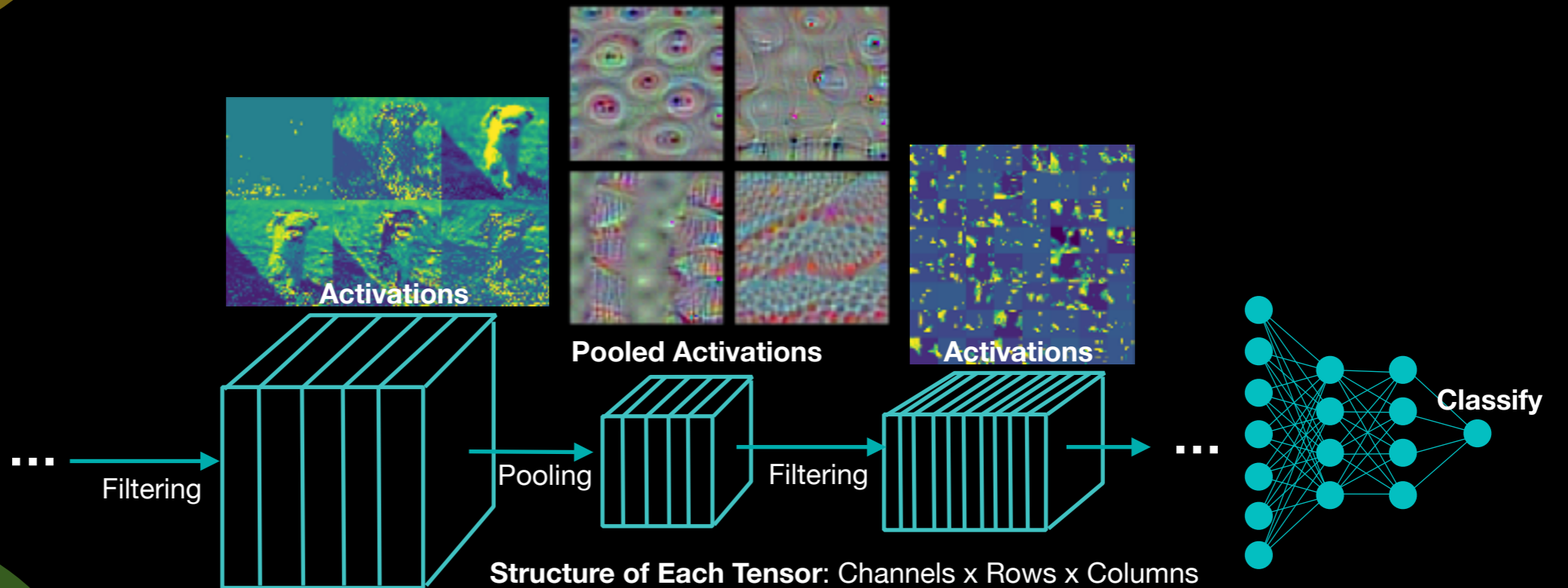
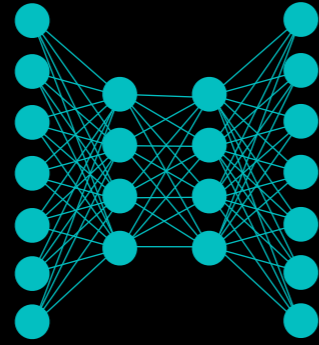
Convolutional Classification



Sequential Processing



Fully Convolutional Learning



Convolutional Classification

Back-propagate to reduce errors
(optimize filter values)

Label Errors

Robotic Partial Nephrectomy Scoring Card

Overall Rubric Scoring

Your GEARs rubric total: **28**

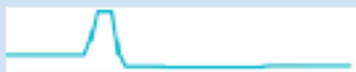
You scored at an **expert** level. Most surgeons score 26 or better.

Your OSATS rubric total: **32**

You scored at an **expert** level. Most surgeons score 32 or better.

Task Specific Rubric Scoring

Surgical Task: Cut



Task Time: 9 mins 57 s
Suggested Video Reviews:
(Click to navigate)
[3 min 12 s](#)

GEARS Total	28
Depth Perception	5
Bimanual Dexterity	5
Efficiency	3
Force Sensitivity	5
Autonomy	5
Robotic Control	5
OSATS Total	32
Respect for Tissue	5
Time & Motion	4
Instrument Handling	5
Inst. Knowledge	5
Assistance	5
Flow of Operation	5
Know. of Procedure	4

Surgical Task: Reconnection



Task Time: 19 mins 5 s
Suggested Video Reviews:
(Click to navigate)
[25 min 36 s](#)

GEARS Total	27
Depth Perception	5
Bimanual Dexterity	4
Efficiency	3
Force Sensitivity	5
Autonomy	5
Robotic Control	5
OSATS Total	31
Respect for Tissue	4
Time & Motion	3
Instrument Handling	5
Inst. Knowledge	5
Assistance	5
Flow of Operation	5
Know. of Procedure	4

Surgical Task: Bolster



Task Time: 9 mins 41 s
Suggested Video Reviews:
None

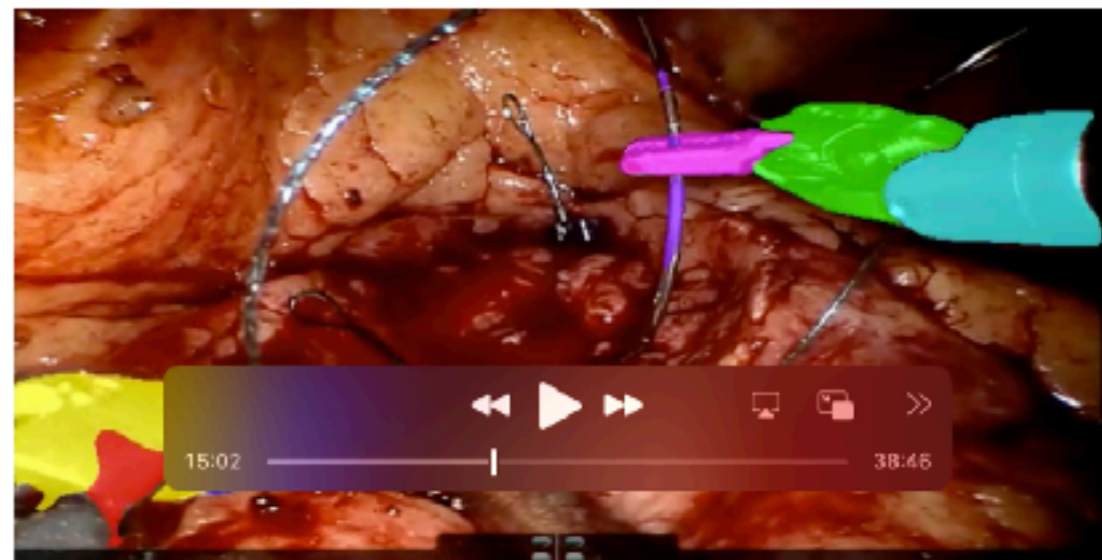
GEARS Total	29
Depth Perception	5
Bimanual Dexterity	5
Efficiency	4
Force Sensitivity	5
Autonomy	5
Robotic Control	5
OSATS Total	30
Respect for Tissue	5
Time & Motion	3
Instrument Handling	4
Inst. Knowledge	5
Assistance	5
Flow of Operation	5
Know. of Procedure	5

GEARS Scoring Explanation

Depth Perception	1	2	3	4	5
Consistently accesses the target, least movements, then slowly			Some follows in reaching the goal, but somewhat quickly.		Directs the instrument to the correct start to the target.
Bimanual skill	1	2	3	4	5
Use only one hand, ignores the non-dominant hand, poor coordination between the two.			Use both hands, but the direction between them is not optimal.		Use both hands in a complementary manner for optimal exposure.
Efficiency	1	2	3	4	5
Many repetitive movements, frequent changes in the thing to do, not progress.			Slow movements, but sequential and reasonable.		Confident, efficient, remains focused on the goal.
Force control	1	2	3	4	5
Jittering, tearing the tissue, damage to structures. Frequent breaking of the suture.			Worse than handling of tissues, less damage occurs. Occasional rupture of the suture.		Proper handling of tissues, proper handling of suture. Without breaking the suture.
Assistance	1	2	3	4	5
Unable to complete the procedure.			The individual is able to complete the task safely, with some guidance from the observer.		Able to complete the task alone, without a guide.
Robot Control	1	2	3	4	5
Do not adjust the position of the hands on the console, frequent collision. The video is not centered.			Occasional contact of hand. Vision is somewhat not sufficient.		Adjusts control of the console. Optimal hand position without collisions.

OSATS Scoring Explanation

Respect for tissue	1	2	3	4	5
Frequently used an unnecessary force on the tissue or vessel, damage by inappropriate use of instruments.			Careful handling of tissue but occasionally caused to overheat tissue damage.		Consistently handled tissues appropriately with minimal damage.
Time and motion	1	2	3	4	5
Many unnecessary steps.			Efficient few steps but some unnecessary steps.		Efficiency of movement and maximum efficiency.
Instrument handling	1	2	3	4	5
Repetitively makes same use of an unusual device with instruments.			Competent use of instruments although occasionally appeared stiff or awkward.		Fluid moves with instruments and re-adjusts less.
Knowledge of instruments	1	2	3	4	5
Frequently asked for the wrong instrument or used an inappropriate instrument.			Knows the names of most instruments and used appropriate instrument for the task.		Obviously familiar with the instruments required and their names.
Use of assistants	1	2	3	4	5
Consistently placed assistants poorly or failed to use assistants.			Good use of assistants most of the time.		Strategically and consistently used assistants to the best advantage at all times.
Flow of operation and forward planning	1	2	3	4	5
Frequently stopped operating or needed to discuss next move.			Demonstrated ability for forward planning with steady progression of operation procedure.		Obviously planned course of operation with effortless flow from one move to the next.
Knowledge of specific procedures	1	2	3	4	5
Broken knowledge. Needed specific instruction for most operation steps.			Knows all important aspects of the operation.		Demonstrated familiarity with all aspects of the operation.



Video Review Portal: See suggested review points shown to the left.

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INTUITIVE
Foundation

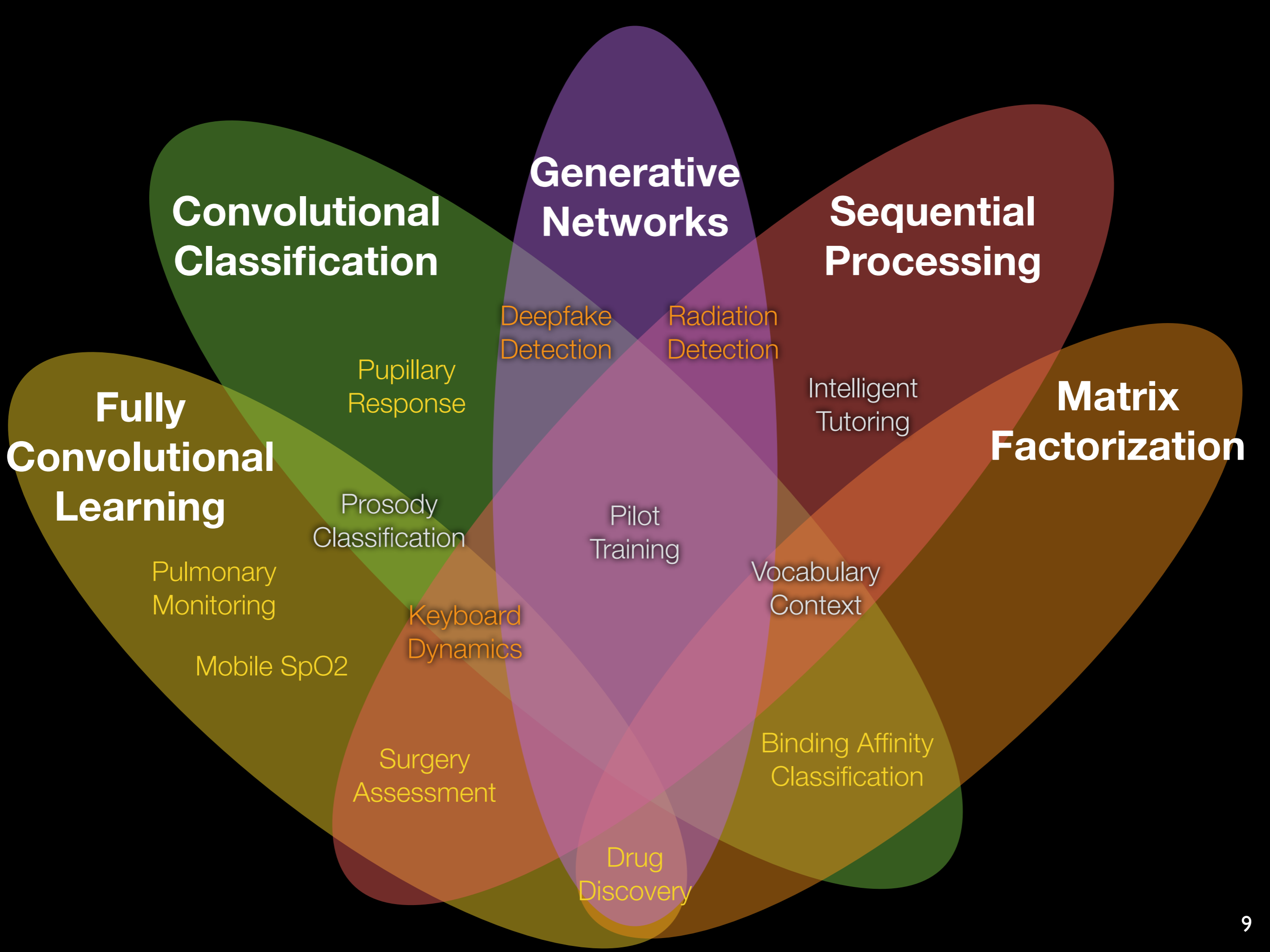


SMU Artificial
Intelligence

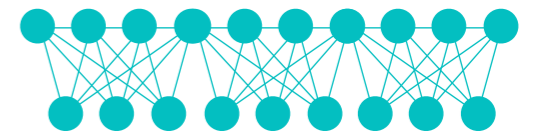
UTSW
Urology

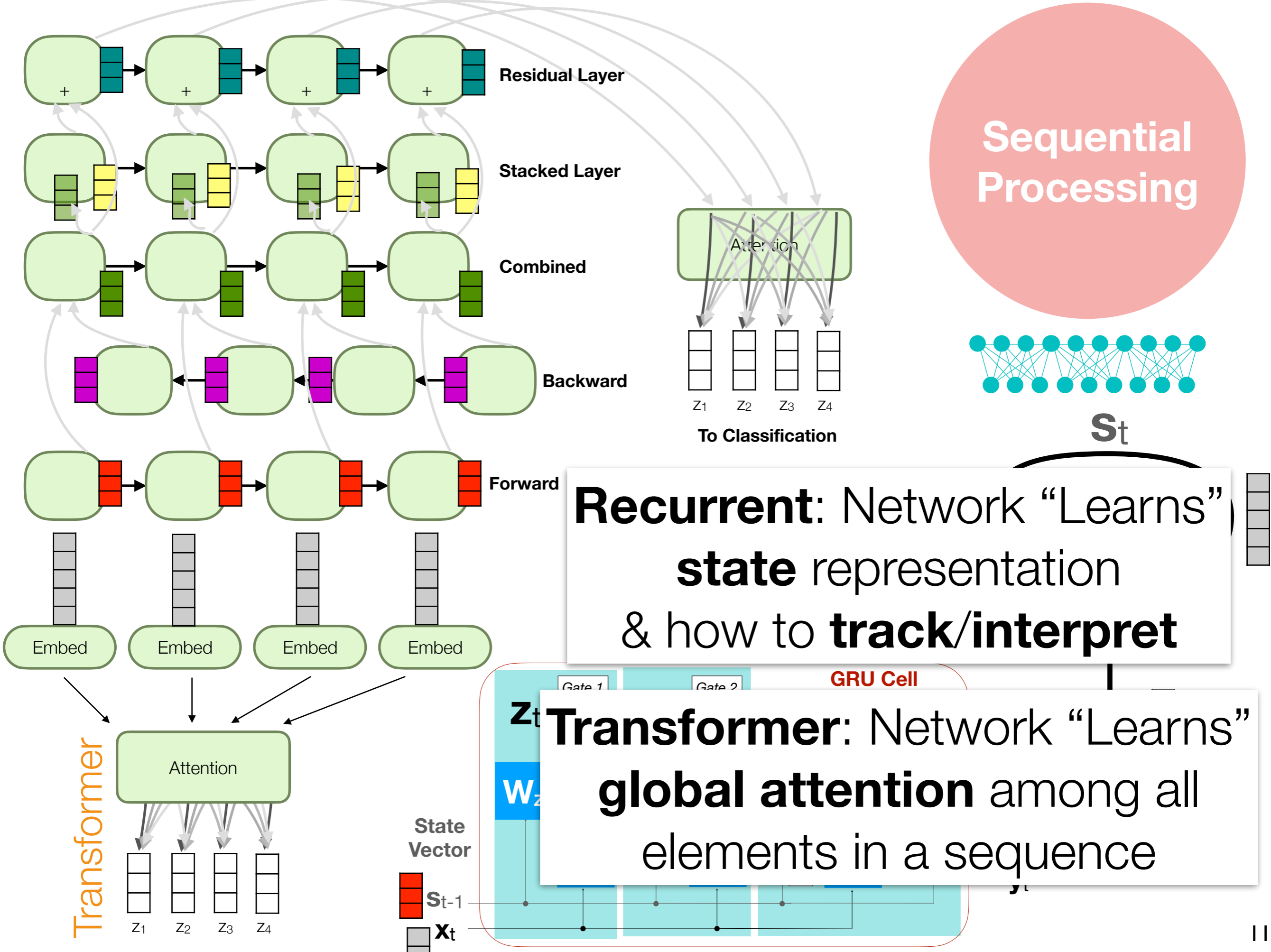
Convolutional Classification

- X. Qu, M. El-Saied, J. Gahan, R. Steinberg, and E.C. Larson (2019). "Machine Learning using a Multi-task Convolutional Neural Networks Can Accurately Provide Robotic Skills Assessment." 2019 World Congress of Endourology.
- Y. Wang, J. Dai, T. Morgan, M. Elsaid, A. Garbens, X. Qu, R. Steinberg, J. Gahan, and E.C. Larson (2021). "Evaluating Robotic-Assisted Surgery Training Videos with Multi-task Convolutional Neural Networks." Journal of Robotic Surgery (JORS), 2021. Doi: 10.1007/s11701-021-01316-2
- Zhongjie Wu, Yihao Wang, Jessica Dai, Tara Morgan, Alaina Garbens, Hal Kominsky, Jeffrey Gahan, & Eric C. Larson (2023) Evaluating Robotic Partial Nephrectomy Surgeons with Fully Convolutional Segmentation and Multitask Attention Networks. JORS 10.1007/s11701-023-01657-0



Sequential Processing



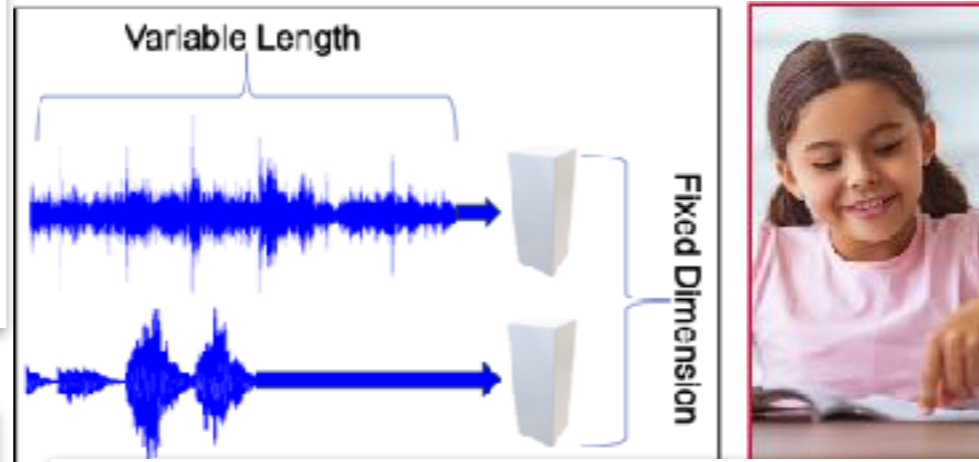


Vocabulary Acquisition Assessment

Prediction

0.78 Model κ with human raters, approaching human level

Transformer Encoder (Layer 1)



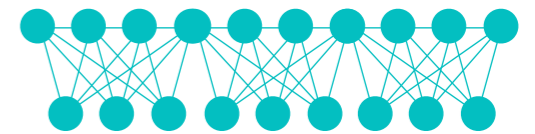
Achieved 86% correctness compared to human rated prosody and 97% correctness of Oral Reading Fluency



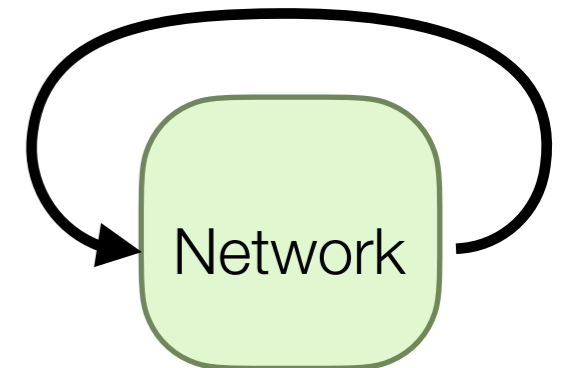
Oral Reading Fluency
Words correct per Minute

Prosody
NAEP Scoring

Sequential Processing



S_t



X_t

- G. Sammit,* Z. Wu,* Y. Wang,* Z. Wu,* A. Kamata, J. Nese, and E. C. Larson (2022). Automated Prosody Classification for Oral Reading Fluency with Quadratic Kappa Loss and Attentive X-vectors. International Conference on Acoustics, Speech, and Signal Processing (ICASSP 2022).
- Yihao Wang, Zhongdi Wu, Akihito Kamata, Joseph Nese, Vedant Nilabh, & Larson, E. (2024) Improving Oral Reading Fluency Assessment through Sub-sequence Matching of Acoustic Word Embeddings. (ICASSP 2024)
- Z. Wu, EC Larson, M. Sano, A. Kamata, N. Gage, and D. Baker (2023). Towards Scalable Vocabulary Acquisition Assessment with BERT. Learning at Scale 2023.

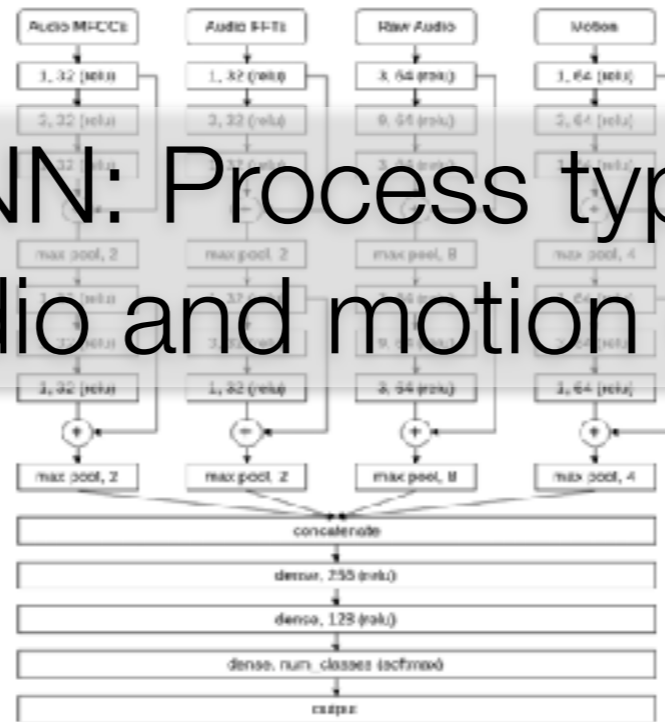
Convolutional Classification

**>90%
Typing
Accuracy**



Typing sounds, table motion

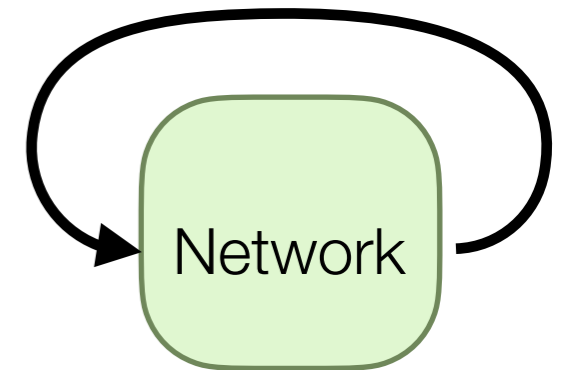
CNN: Process typing audio and motion data



Sequential Processing

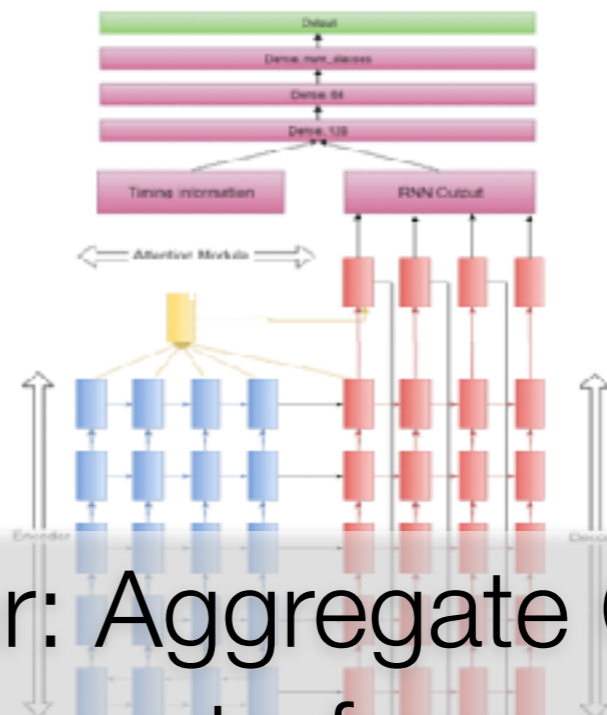


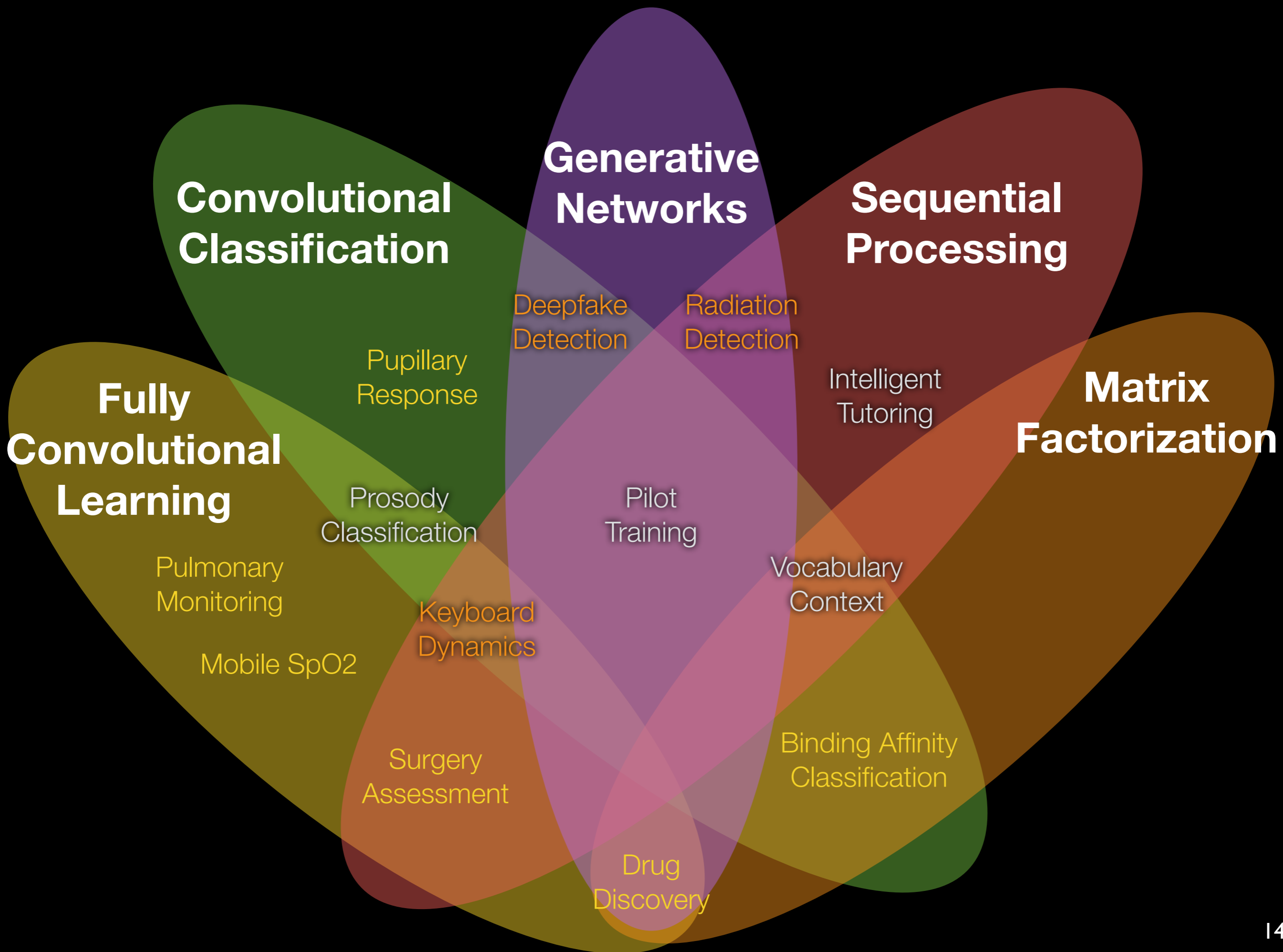
S_t



X_t

Transformer: Aggregate CNN Typing Sequence to form phrases

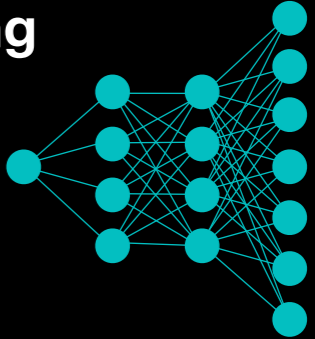




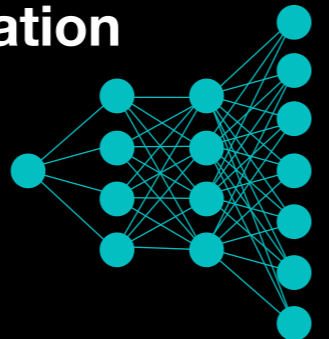
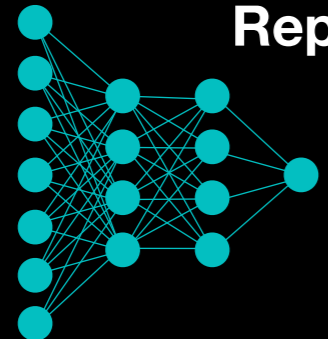
Generative Networks

Swapped Face Detection using Deep Learning and Subjective Assessment
Xinyi Ding^{1*}, Zohreh Razieli², Eric C. Larson¹, Eli V. Olinick², Paul Krueger³ and Michael Hahsler²

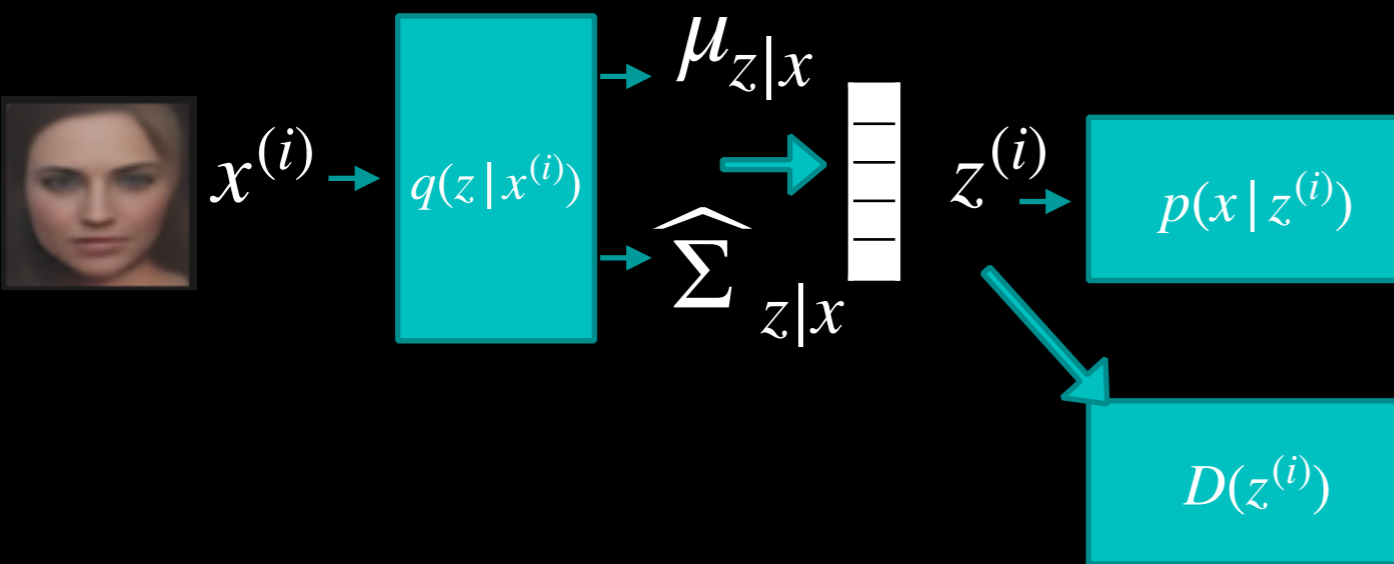
Sampling



Latent Representation



Generated Images (Fake)



Advantage: Allows training of deep networks with fewer labels

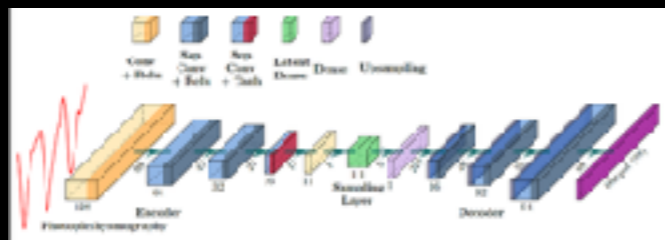
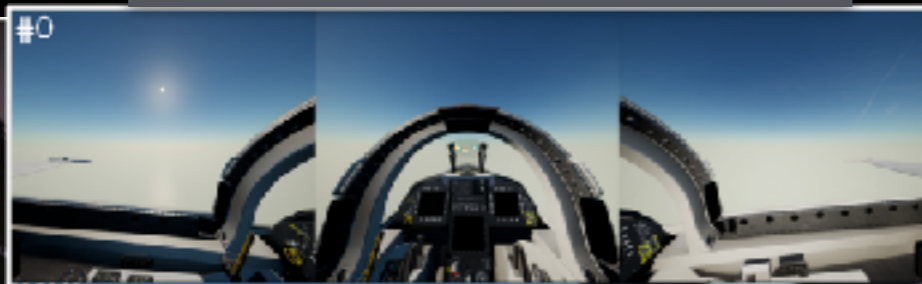
Convolutional Classification

Generative Networks

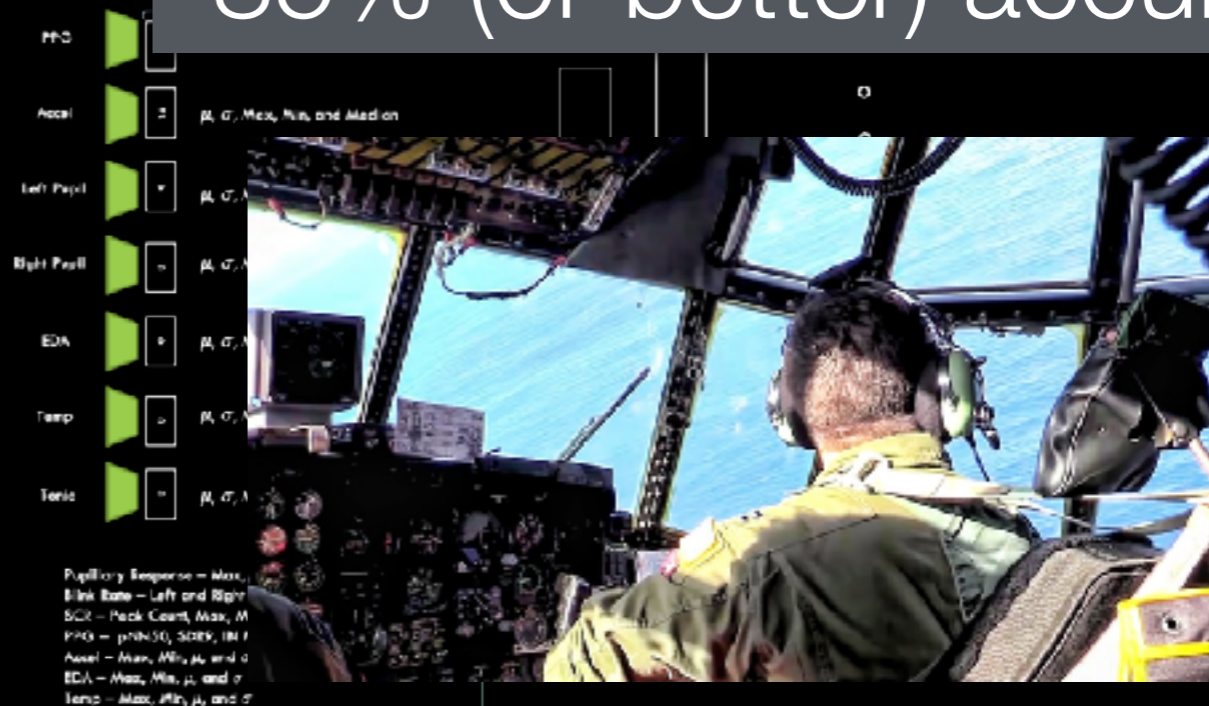
Sequential Processing

Predict pilot cognitive load & situational awareness, 85% (or better) accuracy

Eye Scan Patterns



Wrist Biometrics



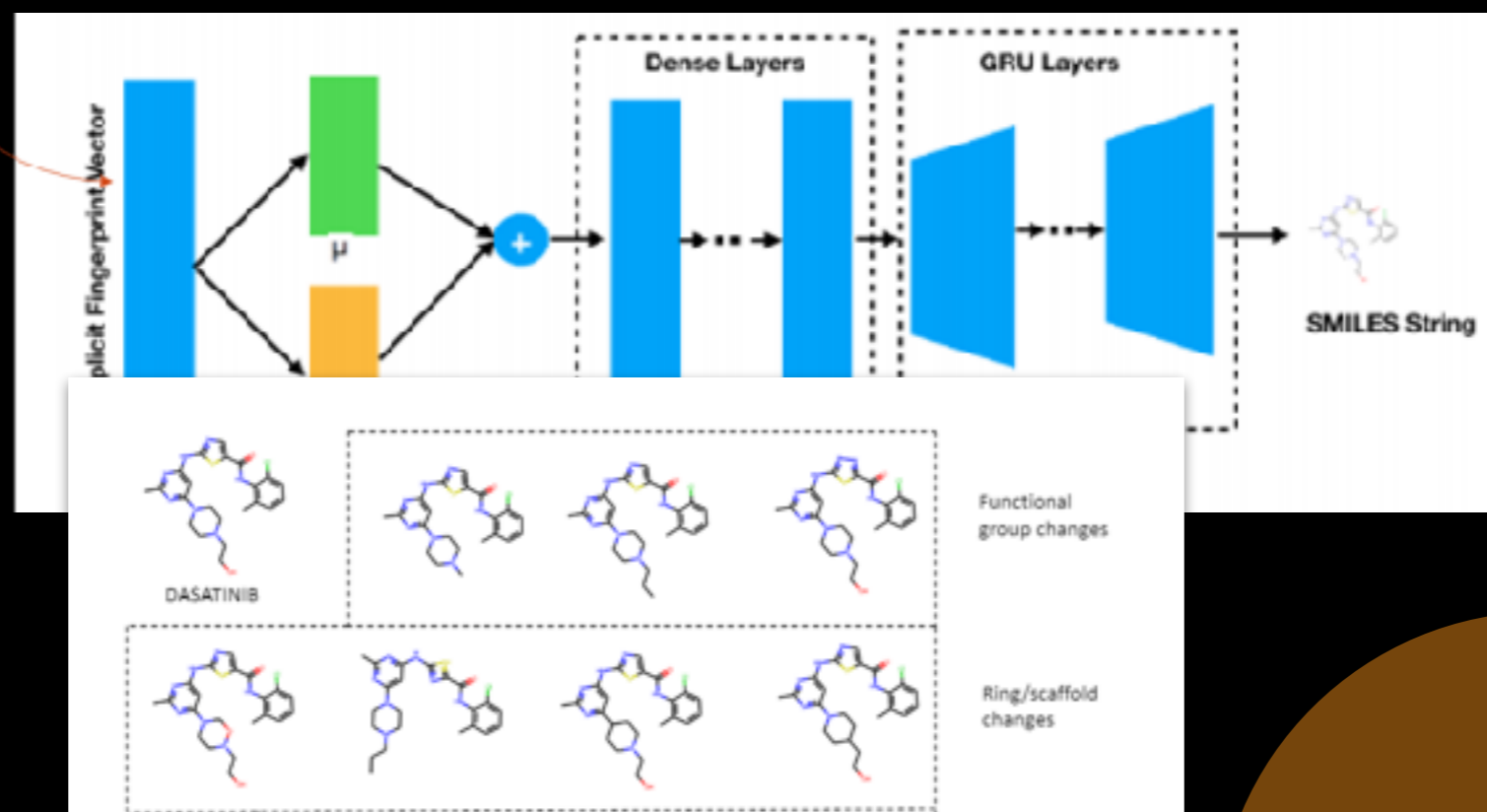
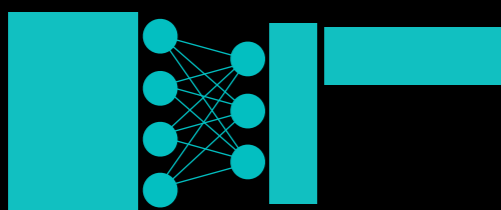
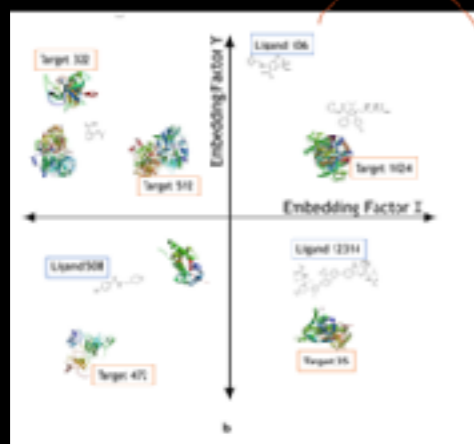
Ratings Domain

- J. Wilson*, S. Nair, S. Scielzo, and E.C. Larson (August 2020). Automatic Gaze Classification for Aviators: Using Multi-task Convolutional Networks as a Proxy for Flight Instructor Observation. International Journal of Aeronautics, Aviation, and Aerospace (IJAAA).
- J. Wilson*, S. Nair, S. Scielzo, and E.C. Larson (March 2021). Cognition-Aware Computing: Objective Measures of Cognitive Load Using Deep Multi-Modal Learning: A Use-Case in Aviation. Proceedings of the ACM Journal on Interactive Mobile Wearable, and Ubiquitous Technology. Vol. 5, Issue. 1, Article 40 (March 2021), 35 pages. <https://doi.org/10.1145/3448111>
- S. Scielzo, J. Wilson*, and E.C. Larson (June 2020). "Towards the Development of an Automated, Real-Time, Objective Measure of Situation Awareness for Pilots." Interservice/Industry Training, Simulation, and Education Conference (I/ITSEC).
- N. Crothers*, Y. Sinha*, S. Scielzo, and E.C. Larson (2022). "Real-Time Situation Awareness Assessment for Pilots via Machine Learning: Constructing an Automated Classification System." Modeling & Simulation (MODSIM) World 2022.
- S. Gibbs, V. Tanner, A. Abrham, S. Scielzo, and E.C. Larson (2024). "Towards the Development of an Automated Trust Classifier." Interservice/Industry Training, Simulation, and Education Conference (I/ITSEC).

Convolutional Classification

Generative Networks

Sequential Processing



Matrix Factorization

- R. Srinivas*, P. Klimovich*, and E.C. Larson. Implicit-descriptor ligand-based virtual screening by means of collaborative filtering. *Journal of Cheminformatics*. 10, no. 1 (2018): 56.
- R. Srinivas*, N. Verma*, E. Kraka, and E.C. Larson (2021). Deep Learning-based Ligand Design using Shared Latent Implicit Fingerprints from Collaborative Filtering. *Journal of Chemical Information and Modeling*.
- M. Makos*, N. Verma*, E.C. Larson, and E. Kraka (2021). Prediction of the Transition State Geometry via Generative Adversarial Network. *The Journal of Chemical Physics*.
- H. Tian*, X. Jiang*, F. Trozzi*, S. Xiao, E. C. Larson and P. Tao (2021). Explore protein conformational space with variational autoencoder. *Journal on Frontiers in Molecular Biosciences*, section Biological Modeling and Simulation (Frontiers).

Convolutional Classification

Generative Networks

Sequential Processing

Matrix Factorization

Fully Convolutional Learning

Deepfake Detection

Radiation Detection

Pupillary Response

Intelligent Tutoring

Prosody Classification

Pilot Training

Vocabulary Context

Pulmonary Monitoring

Keyboard Dynamics

Mobile SpO2

Surgery Assessment

Binding Affinity Classification

Drug Discovery

- Health
- Security
- Education

Application



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O'Donnell Data Science and Research Computing Institute

Our mission is to perform multi-disciplinary research in data science, high performance computing, AI/ML, and future technologies.

SMU's O'Donnell Data Science and Research Computing Institute mission is to **perform multi-disciplinary research** in data science, **high performance computing**, AI/ML, and **future technologies**. We serve as a gateway to SMU's HPC, **developing connections** between our faculty affiliates and government agencies, industry, and nonprofit organizations.

Fairness-aware Multimodal AI for Healthcare Data (DSI FRAG)

Adapting Electronic Health Record Analysis with Fair Input Modalities

O'Donnell Data Science and Research
Computing Institute



Mehak Gupta
Assistant
Professor in
Comp. Sci.

Fairness-aware fusion

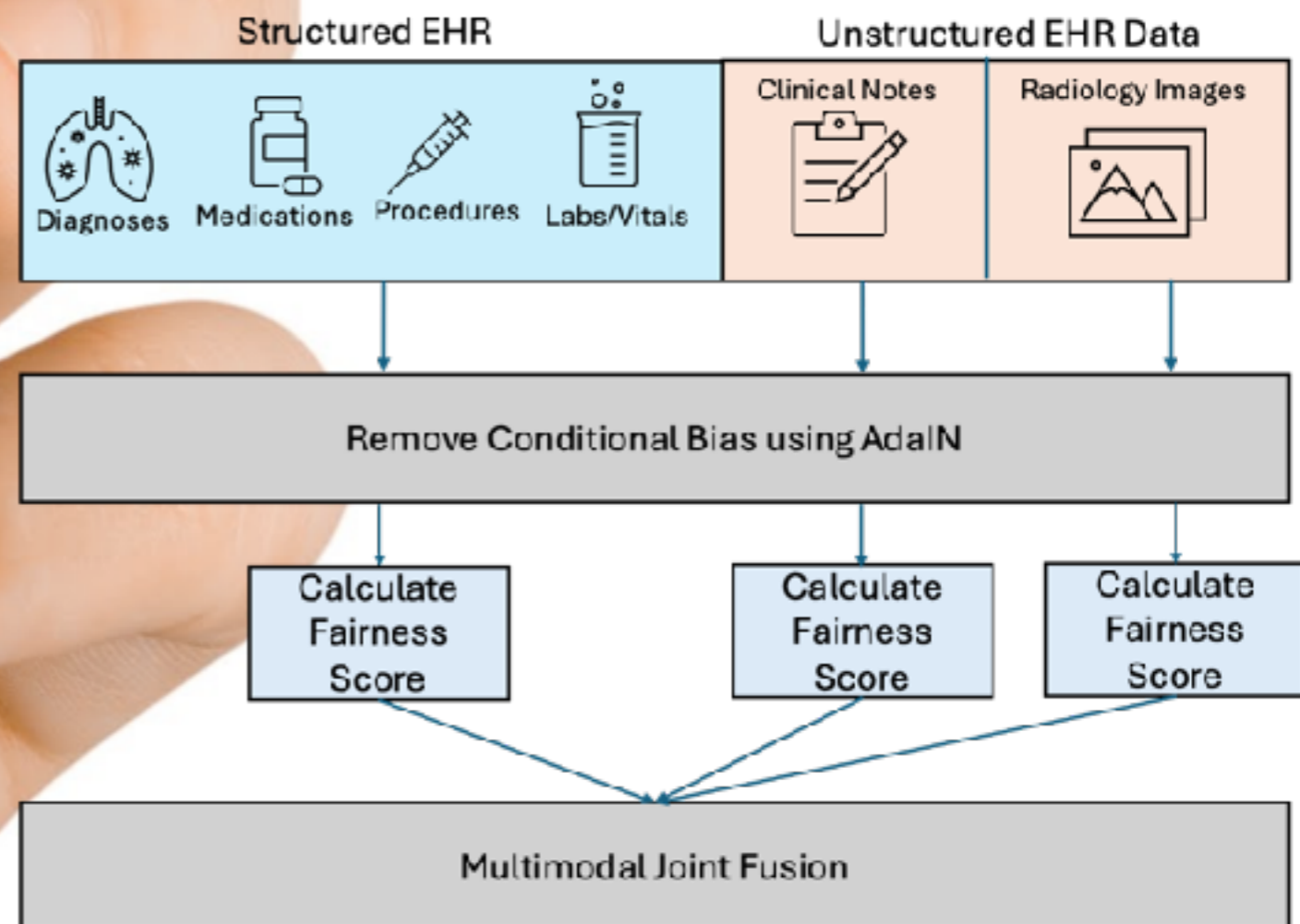
- (+) Fairness modality scoring
- (+) Joint weighted fusion

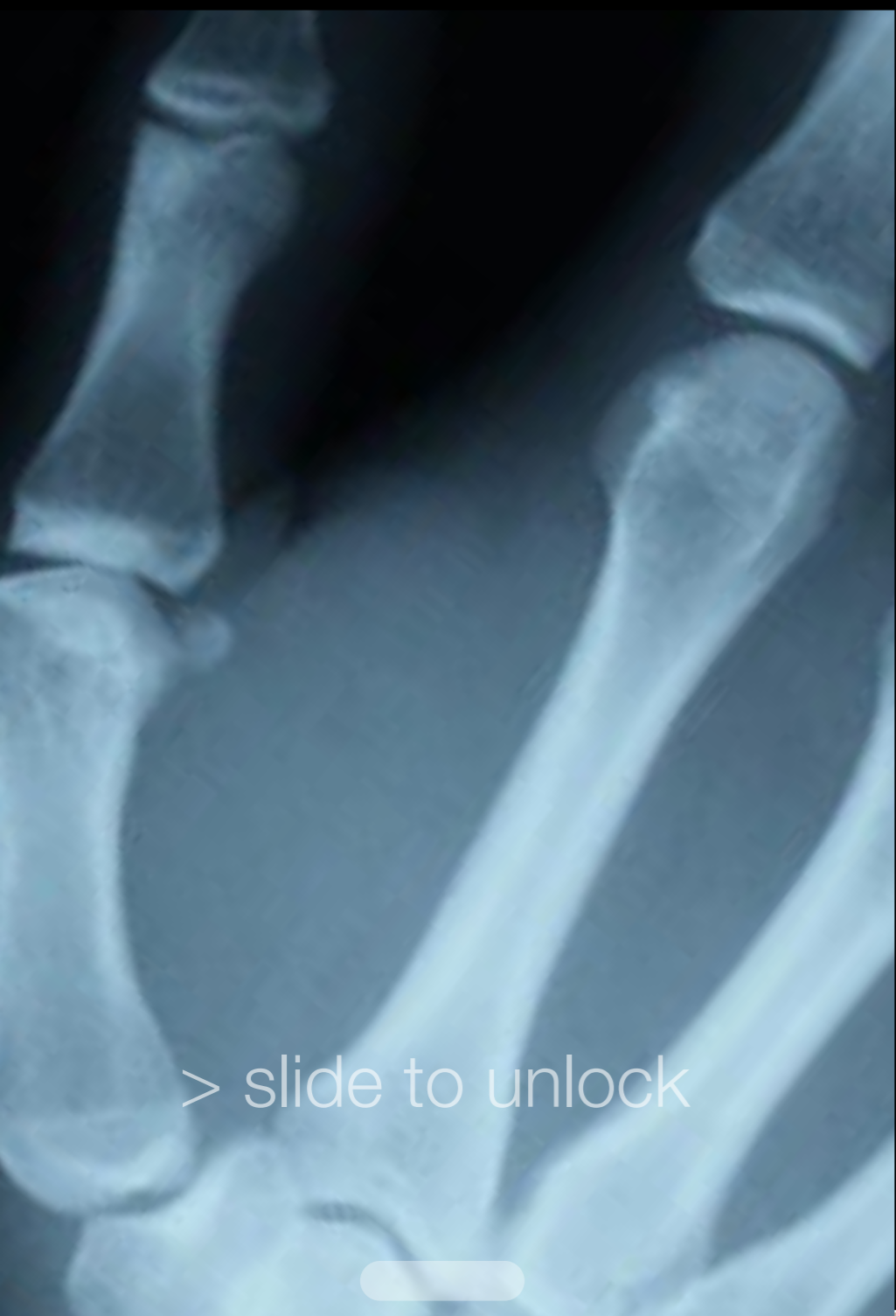
Non-linear refinement

- (+) Train bimodal \rightarrow trimodal models by refining residual losses

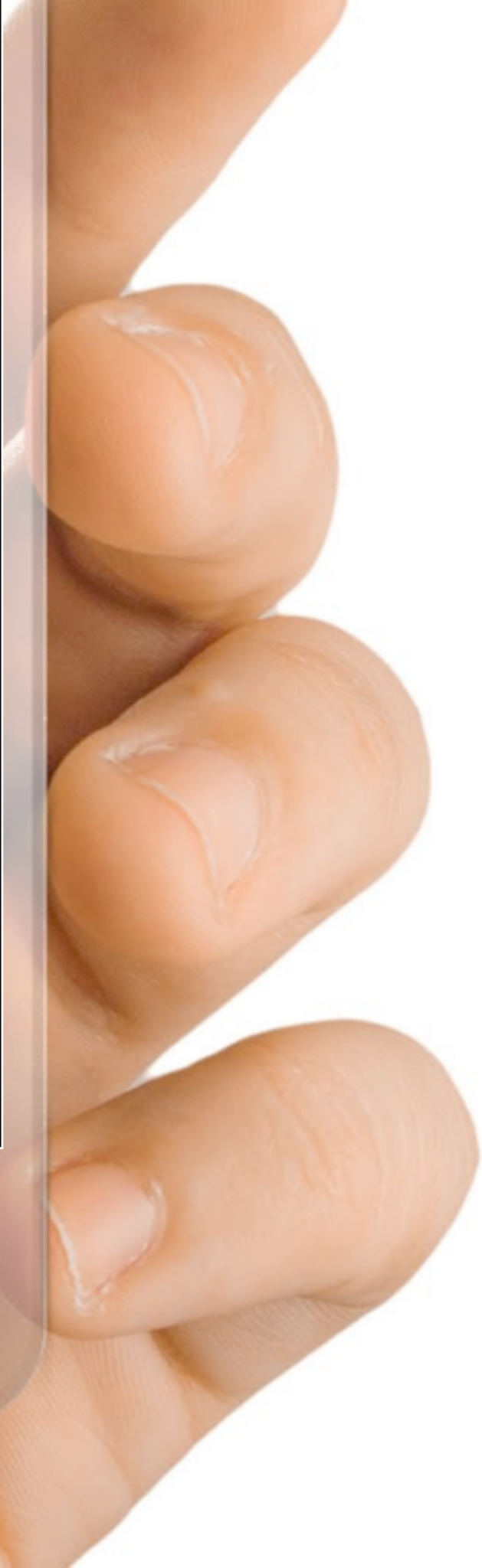
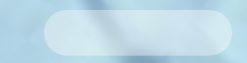
Fairness Evaluation

- (+) Error Distribution Disparity Index





> slide to unlock



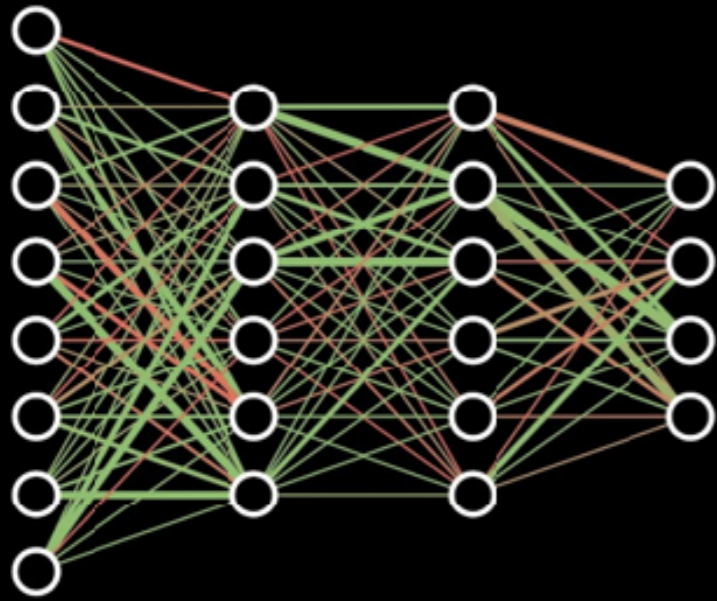
Thank You!

Ubiquitous Machine Learning

deep data representation for next generation systems

Collaborators and Acknowledgments:

Thank You!



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eclarson@smu.edu

- Clay Harper
- Yihao Wang
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- Suku Nair
- Sandro Scielzo
- Bruce Gnade
- Michael Hahsler
- Akihito Kamata
- Doris Baker

SMU O'Donnell Institute Speaker Series, HPC, September 2024

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Bobby B. Lyle Endowed Professor in Engineering Innovation
Associate Professor in Computer Science

